Cook continua as a tool in topological dynamics

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Talk dedicated to the memory of Věra Trnková

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L. Snoha, X. Ye, R. Zhang, *Topology and topological sequence entropy*, Sci. China Math. **63** (2020), no. 2, 205–296.

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1. Cook continua

Cook continuum

= a nondegenerate metric continuum $\ensuremath{\mathbb{C}}$ such that

$$\left. egin{array}{l} \mathcal{K} \subseteq \mathfrak{C} \ {
m subcontinuum} \\ f: \mathcal{K}
ightarrow \mathfrak{C} \ {
m continuous} \end{array}
ight\} \Rightarrow f = \ {
m identity} \ {
m or} \ {
m constant}$$

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- Existence of Cook continua: Cook 1967
- Cook continuum in the plane: Maćkowiak 1986

2. Supremum topological sequence entropy

Topological sequence entropy (can be used to distinguish between systems with zero topological entropy, Goodman 1974).

(X, T) topological dynamical system (X compact, T continuous) $A = (a_0 < a_1 < \cdots)$ a sequence of nonnegative integers U = open cover of X

$$h^{\mathcal{A}}(\mathcal{T},\mathcal{U}) = \limsup_{n o \infty} rac{1}{n} \log \mathcal{N}\left(igvee_{i=0}^{n-1} \mathcal{T}^{-a_i}(\mathcal{U})
ight)$$

 $\mathcal{N}(\mathcal{V}) = \text{minimal card.}$ of a subcover chosen from \mathcal{V}

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$$h^{A}(T) = \sup_{\mathcal{U}} h^{A}(T, \mathcal{U})$$
 ...top. seq. entropy of T w.r.t. A

2. Supremum topological sequence entropy Supremum topological sequence entropy of *T*:

$$\frac{h^*(T)}{A} = \sup_A h^A(T)$$

A way to compute $h^*(T)$ (Kerr, Li 2007, Huang, Ye 2009):

$$h^*(T) = \sup\{\log k : \exists \text{ intrinsic IN-tuple of length } k\}$$

Intrinsic IN-tuple of length k =

 $(x_1, \ldots, x_k) \in X^k$, pairwise different, for any nbhds U_1, \ldots, U_k there exist arbitrarily long finite independence sets of times

 $I = \{3, 4, 9\} \text{ is an independence set of times for } U_1, \dots, U_k \text{ if for any choice of indices } s(3), s(4), s(9) \in \{1, \dots, k\} \text{ there exists } x \in X : T^3 x \in U_{s(3)}, T^4 x \in U_{s(4)}, T^9 x \in U_{s(9)}$

3. Known possibilities for the sets of values of supremum topological sequence entropy on various spaces

As a consequence of the formula $h^*(T) = \sup\{\log k : ...\}$ we get:

$$S(X) := \{h^*(T) : T \text{ is continuous } X o X\}$$

 $\subseteq \{0, \log 2, \log 3, \dots\} \cup \{\infty\}$

3 previously known possibilities:

S(X) = {0}
0-dim spaces with finite derived sets (Ye, Zhang 2008)

- $\blacktriangleright S(X) = \{0, \log 2, \log 3, \dots\} \cup \{\infty\}$
 - O-dim spaces with infinite derived sets (Tan, Ye, Zhang 2010)
 - some dendrites (Tan, Ye, Zhang 2010)
 - ▶ manifolds of dimension ≥ 2 (Tan, Ye, Zhang 2010)

4. Theorem describing all possibilities

We have:

- ► $S(X) \subseteq \{0, \log 2, \log 3, ...\} \cup \{\infty\}$... explained above
- ▶ $S(X) \supseteq \{0\}$... consider T = identity or T = constant map

Therefore the following theorem describes all possibilities for S(X):

Theorem.
$$\{0\} \subseteq A \subseteq \{0, \log 2, \dots\} \cup \{\infty\}$$

 $\Rightarrow \exists$ one-dim. continuum X_A with $S(X_A) = A$

Remarks:

- The same result for $S_{\text{hom}}(X) = \{h^*(T) : T \text{ is a homeomorphism } X \to X\}$
- Also for some group actions (under some assumptions on the group), but in full generality the problem remains open.

How to construct a continuum X with $S(X) = \{0, \infty\}$:

(= the easiest of the previously unknown cases) Ingredients: Pairwise disjoint subcontinua $\mathcal{K}_0, \mathcal{K}_1, \mathcal{K}_2, \ldots$ of a planar Cook continuum.

(These are non-homeomorphic Cook continua. Instead of "a copy of \mathcal{K}_i " we will write just " \mathcal{K}_i ".) In each \mathcal{K}_i we fix the 'first point' and the 'last point'. (= the points where we will glue them)

1st step: An auxiliary system (X_1, T_1) with $h^*(T_1) = \infty$:

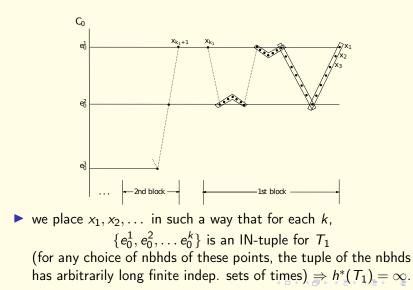
 X₁ := K₀ ⊔ {x₁, x₂, x₃, ... } K₀ = Cook continuum in a vertical plane, the sequence (x_n)_{n=1}[∞] approaches K₀ from the right

•
$$T_1|_{\mathcal{K}_0} = \text{identity}$$

•
$$T_1(x_n) = x_{n+1}, n = 1, 2, ...$$

• distances between x_n and x_{n+1} tend to zero $\Rightarrow T_1$ continuous

▶ 'vertical coordinates' of the points x_n are in a fixed dense set $\{e_0^1, e_0^2, e_0^3, \dots\} \subseteq \mathcal{K}_0$

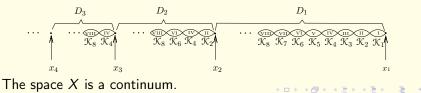


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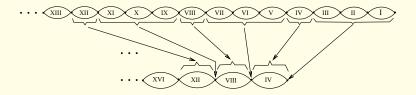
5. Idea of the proof – 'snakes' of Cook continua 2nd step: We join x_n and x_{n+1} by a set D_n , n = 1, 2, ... We obtain $X = \mathcal{K}_0 \sqcup \bigcup_{n=1}^{\infty} D_n$:



The sets D_n are obtained by gluing together copies of some of the Cook continua $\mathcal{K}_1, \mathcal{K}_2, \ldots$:



3rd step: We extend $T_1: X_1 \to X_1$ to a continuous map $T: X \to X$, which maps D_1 onto D_2 , D_2 onto D_3 , (In fact D_m can be continuously mapped onto D_M if and only if $m \le M$:



The unique continuous surjective map $D_1
ightarrow D_3$

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We have obtained a dynamical system (X, T). It contains, as a subsystem, the dynamical system (X_1, T_1) we started with.

4th step: We prove that $S(X) = \{0, \infty\}$:

• 0 is always in S(X).

▶ $\infty \in S(X)$ since $h^*(T) = \infty$ (indeed, $h^*(T) \ge h^*(T_1) = \infty$).

• If $F: X \to X$ is continuous then, using the structure of X, one can show that

- either F is very simple, with h*(F) = 0 (in fact some iterate F^N is a retraction of X onto Fix(F)),
- or $F = T^N$ on the whole X except perhaps the beginning part $D_1 \cup \cdots \cup D_m$ for some m. Then

 $h^*(F) \ge h^*(T^N) \ge h^*(T_1^N) = h^*(T_1) = \infty$

and so $h^*(F) = \infty$.

Remark. Other sets, say $A = \{0, \log 3, \log 33, \log 333, ...\}$, require much more complicated spaces but the main idea – gluing Cook continua – is the same.