## Cook continua as a tool in topological dynamics

L'ubomír Snoha<br>Matej Bel University, Banská Bystrica, Slovakia

(joint work with Xiangdong Ye and Ruifeng Zhang)
Talk dedicated to the memory of Věra Trnková
TOPOSYM, Prague, July 25 - 29, 2022

July 29, 2022

1. Cook continua
2. Supremum topological sequence entropy
3. Known possibilities for the sets of values of supremum topological sequence entropy on various spaces
4. Theorem describing all possibilities
5. Idea of the proof - 'snakes' of Cook continua

R L'. Snoha, X. Ye, R. Zhang, Topology and topological sequence entropy, Sci. China Math. 63 (2020), no. 2, 205-296.

## 1. Cook continua

## Cook continuum

$=$ a nondegenerate metric continuum $\mathcal{C}$ such that

$$
\left.\begin{array}{l}
K \subseteq \mathcal{C} \text { subcontinuum } \\
f: K \rightarrow \mathcal{C} \text { continuous }
\end{array}\right\} \Rightarrow f=\text { identity or constant }
$$

- Existence of Cook continua: Cook 1967
- Cook continuum in the plane: Maćkowiak 1986


## 2. Supremum topological sequence entropy

Topological sequence entropy (can be used to distinguish between systems with zero topological entropy, Goodman 1974).
( $X, T$ ) topological dynamical system ( $X$ compact, $T$ continuous) $A=\left(a_{0}<a_{1}<\cdots\right)$ a sequence of nonnegative integers $\mathcal{U}=$ open cover of $X$

$$
h^{A}(T, \mathcal{U})=\lim \sup _{n \rightarrow \infty} \frac{1}{n} \log \mathcal{N}\left(\bigvee_{i=0}^{n-1} T^{-a_{i}}(\mathcal{U})\right)
$$

$$
\mathcal{N}(\mathcal{V})=\text { minimal card. of a subcover chosen from } \mathcal{V}
$$

$$
h^{A}(T)=\sup h^{A}(T, \mathcal{U}) \quad \text {...top. seq. entropy of } T \text { w.r.t. } A
$$

- $A=(0,1,2, \ldots) \Rightarrow h^{A}(T)=h(T)$, top. entropy of $T$
- more generally: $h^{(0, k, 2 k, 3 k, \ldots)}(T)=h\left(T^{k}\right)=k h(T)$


## 2. Supremum topological sequence entropy

Supremum topological sequence entropy of $T$ :

$$
h^{*}(T)=\sup _{A} h^{A}(T)
$$

- $h(T)>0 \Rightarrow h^{*}(T)=\infty$
- $h^{*}\left(T^{n}\right)=h^{*}(T), n=1,2, \ldots(n \in \mathbb{Z} \backslash\{0\}$ if $T$ is homeo $)$

A way to compute $h^{*}(T)$ (Kerr, Li 2007, Huang, Ye 2009):

$$
h^{*}(T)=\sup \{\log k: \exists \underbrace{\text { intrinsic IN-tuple of length } k}\}
$$

Intrinsic IN-tuple of length $k=$ $\left(x_{1}, \ldots, x_{k}\right) \in X^{k}$, pairwise different, for any nbhds $U_{1}, \ldots, U_{k}$ there exist arbitrarily long finite independence sets of times
$I=\{3,4,9\}$ is an independence set of times for $U_{1}, \ldots, U_{k}$ if for any choice of indices $s(3), s(4), s(9) \in\{1, \ldots, k\}$ there exists $x \in X: T^{3} x \in U_{s(3)}, T^{4} x \in U_{s(4)}, T^{9} x \in U_{s(9)}$
3. Known possibilities for the sets of values of supremum topological sequence entropy on various spaces

As a consequence of the formula $h^{*}(T)=\sup \{\log k: \ldots\}$ we get:

$$
\begin{aligned}
S(X): & =\left\{h^{*}(T): T \text { is continuous } X \rightarrow X\right\} \\
& \subseteq\{0, \log 2, \log 3, \ldots\} \cup\{\infty\}
\end{aligned}
$$

3 previously known possibilities:

- $S(X)=\{0\}$
- 0-dim spaces with finite derived sets (Ye, Zhang 2008)
- $S(X)=\{0, \log 2\} \cup\{\infty\}$
- interval (Canovas 2004), ..., finite graphs (Tan 2011)
- $S(X)=\{0, \log 2, \log 3, \ldots\} \cup\{\infty\}$
- 0-dim spaces with infinite derived sets (Tan, Ye, Zhang 2010)
- some dendrites (Tan, Ye, Zhang 2010)
- manifolds of dimension $\geq 2$ (Tan, Ye, Zhang 2010)


## 4. Theorem describing all possibilities

We have:

- $S(X) \subseteq\{0, \log 2, \log 3, \ldots\} \cup\{\infty\} \ldots$ explained above
- $S(X) \supseteq\{0\} \ldots$ consider $T=$ identity or $T=$ constant map

Therefore the following theorem describes all possibilities for $S(X)$ :
Theorem. $\{0\} \subseteq A \subseteq\{0, \log 2, \ldots\} \cup\{\infty\}$ $\Rightarrow \exists$ one-dim. continuum $X_{A}$ with $S\left(X_{A}\right)=A$

Remarks:

- The same result for $S_{\text {hom }}(X)=\left\{h^{*}(T): T\right.$ is a homeomorphism $\left.X \rightarrow X\right\}$
- Also for some group actions (under some assumptions on the group), but in full generality the problem remains open.


## 5. Idea of the proof - 'snakes' of Cook continua

How to construct a continuum $X$ with $S(X)=\{0, \infty\}$ :
( $=$ the easiest of the previously unknown cases)
Ingredients: Pairwise disjoint subcontinua $\mathcal{K}_{0}, \mathcal{K}_{1}, \mathcal{K}_{2}, \ldots$ of a planar Cook continuum.
(These are non-homeomorphic Cook continua. Instead of "a copy of $\mathcal{K}_{i}$ " we will write just " $\mathcal{K}_{i}{ }^{\prime}$.)
In each $\mathcal{K}_{i}$ we fix the 'first point' and the 'last point'.
( $=$ the points where we will glue them)
1st step: An auxiliary system $\left(X_{1}, T_{1}\right)$ with $h^{*}\left(T_{1}\right)=\infty$ :

- $X_{1}:=\mathcal{K}_{0} \sqcup\left\{x_{1}, x_{2}, x_{3}, \ldots\right\}$
$\mathcal{K}_{0}=$ Cook continuum in a vertical plane, the sequence $\left(x_{n}\right)_{n=1}^{\infty}$ approaches $\mathcal{K}_{0}$ from the right
- $\left.T_{1}\right|_{\mathcal{K}_{0}}=$ identity
- $T_{1}\left(x_{n}\right)=x_{n+1}, n=1,2, \ldots$
- distances between $x_{n}$ and $x_{n+1}$ tend to zero $\Rightarrow T_{1}$ continuous


## 5. Idea of the proof - 'snakes' of Cook continua

- 'vertical coordinates' of the points $x_{n}$ are in a fixed dense set $\left\{e_{0}^{1}, e_{0}^{2}, e_{0}^{3}, \ldots\right\} \subseteq \mathcal{K}_{0}$

- we place $x_{1}, x_{2}, \ldots$ in such a way that for each $k$, $\left\{e_{0}^{1}, e_{0}^{2}, \ldots e_{0}^{k}\right\}$ is an IN-tuple for $T_{1}$
(for any choice of nbhds of these points, the tuple of the nbhds has arbitrarily long finite indep. sets of times) $\Rightarrow h^{*}\left(T_{1}\right)_{\equiv}=\infty$.


## 5. Idea of the proof - 'snakes' of Cook continua

 2nd step: We join $x_{n}$ and $x_{n+1}$ by a set $D_{n}, n=1,2, \ldots$. We obtain $X=\mathcal{K}_{0} \sqcup \bigcup_{n=1}^{\infty} D_{n}$ :

The sets $D_{n}$ are obtained by gluing together copies of some of the Cook continua $\mathcal{K}_{1}, \mathcal{K}_{2}, \ldots$ :


The space $X$ is a continuum.

## 5. Idea of the proof - 'snakes' of Cook continua

3rd step: We extend $T_{1}: X_{1} \rightarrow X_{1}$ to a continuous map
$T: X \rightarrow X$, which maps $D_{1}$ onto $D_{2}, D_{2}$ onto $D_{3}, \ldots$
(In fact $D_{m}$ can be continuously mapped onto $D_{M}$ if and only if $m \leq M$ :


The unique continuous surjective map $D_{1} \rightarrow D_{3}$
We have obtained a dynamical system $(X, T)$. It contains, as a subsystem, the dynamical system $\left(X_{1}, T_{1}\right)$ we started with.

## 5. Idea of the proof - 'snakes' of Cook continua

4th step: We prove that $S(X)=\{0, \infty\}$ :

- 0 is always in $S(X)$.
- $\infty \in S(X)$ since $h^{*}(T)=\infty$ (indeed, $h^{*}(T) \geq h^{*}\left(T_{1}\right)=\infty$ ).
- If $F: X \rightarrow X$ is continuous then, using the structure of $X$, one can show that
- either $F$ is very simple, with $h^{*}(F)=0$ (in fact some iterate $F^{N}$ is a retraction of $X$ onto $\left.\operatorname{Fix}(F)\right)$,
- or $F=T^{N}$ on the whole $X$ except perhaps the beginning part $D_{1} \cup \cdots \cup D_{m}$ for some $m$. Then

$$
h^{*}(F) \geq h^{*}\left(T^{N}\right) \geq h^{*}\left(T_{1}^{N}\right)=h^{*}\left(T_{1}\right)=\infty
$$

and so $h^{*}(F)=\infty$.
Remark. Other sets, say $A=\{0, \log 3, \log 33, \log 333, \ldots\}$, require much more complicated spaces but the main idea - gluing Cook continua - is the same.

